

ISEE 3MT (システム情報 3MT)

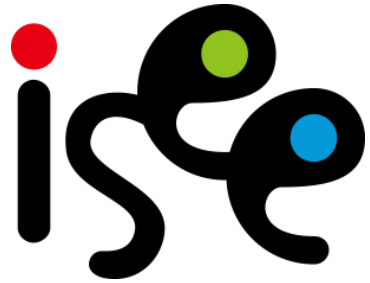
“3MT” means Three Minute Thesis. Ph.D. course students will present their research in three minutes. Today, ten students will come. This is a competition. Please vote for the most impressive presenter. The 1st to 3rd outstanding presenters will receive the awards. Please google “ISEE 3MT” and find the voting site in the HP of ISEE 3MT.



“3MT”とは、Three Minute Thesisを意味します。博士課程の学生が自身の研究を3分間でプレゼンテーションします。本日は10名の学生が登壇します。発表後に投票を行いますので、皆さん、審査をお願いいたします。詳細は「ISEE 3MT」で検索するとHPに投票サイトへのリンクがあります。1位から3位には賞品が贈呈されます。



<https://www.isee.kyushu-u.ac.jp/3mt.html>



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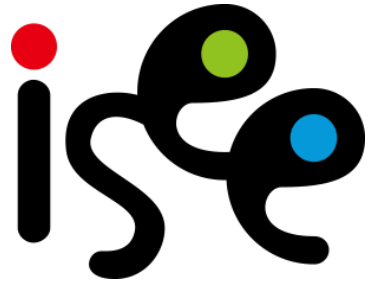
	1st 1位	2nd 2位	3rd 3位
Tomoya Itsuka	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
Pratiksha Mundhe	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
Jeongho Ahn	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
Liangchen Sun	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
Mohamed Mehfoud Bouh	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
Menatallah Fateen	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>

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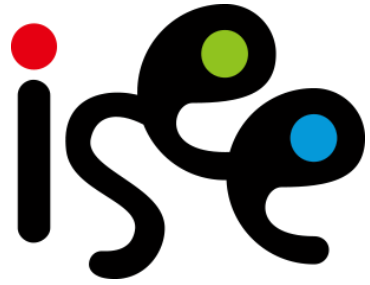
The same link is also on the moodle page of the ISEE 3MT 2025:

<https://moodle.s.kyushu-u.ac.jp/course/view.php?id=62261>



ISEE 3MT Program

Start	End	Title	Presenter	Lab
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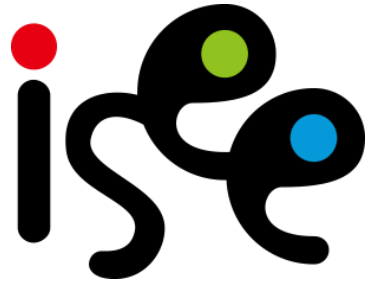
ISEE 3MT

Opening

from

Prof. Makoto Yokoo

Dean of ISEE



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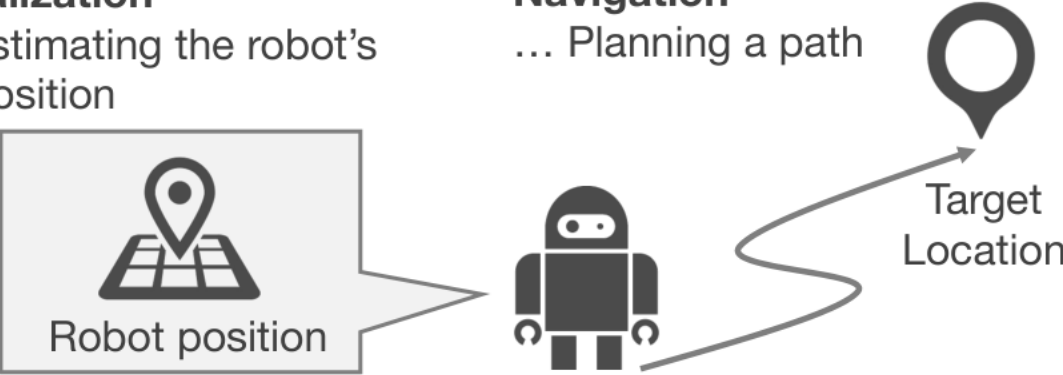
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Indoor Robot Localization with **Wireless Distance Sensors**

I **Accurate and Fast Localization** is key to autonomous driving for robot services

Localization
... Estimating the robot's position

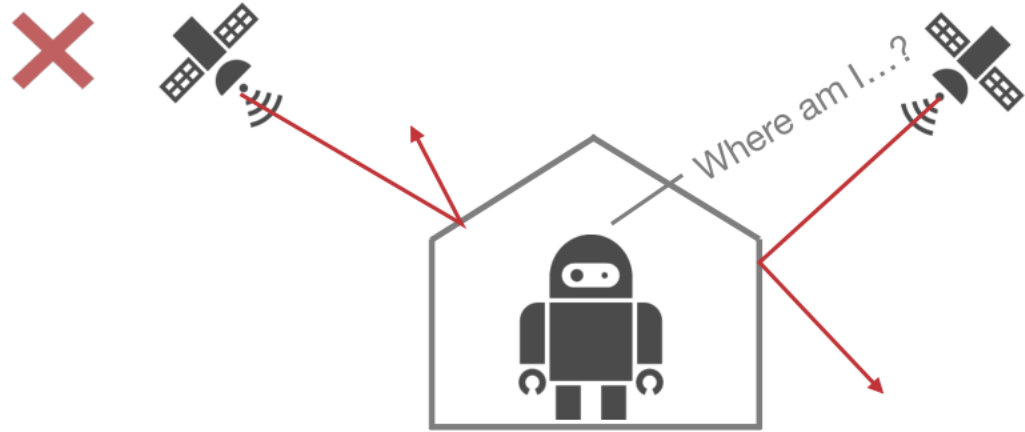
Navigation
... Planning a path



Robot position

Target Location


II **GPS / GNSS is Unavailable** in Indoor Environments



Where am I...?


III **Wireless Distance Sensors** measure Beacon-to-Beacon Distance

✓



- Ultra-Wide Band
- Ultrasonic

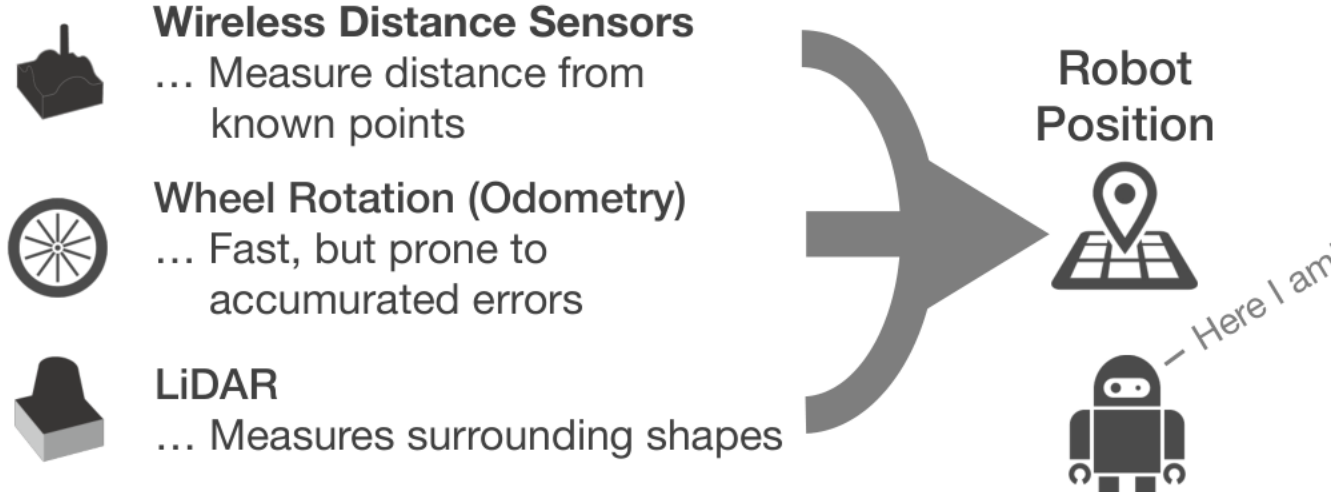
✗



Obstacles

Multipath Effect: measures reflected paths from walls or ceilings

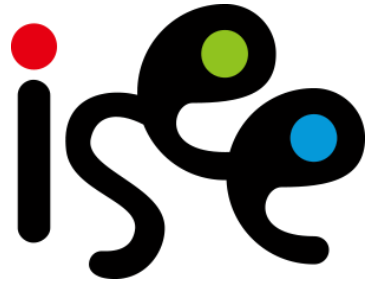
IV **Sensor Fusion** enables **Accurate and Fast Localization** in Indoor Environments



- Wireless Distance Sensors**
... Measure distance from known points
- Wheel Rotation (Odometry)**
... Fast, but prone to accumulated errors
- LiDAR**
... Measures surrounding shapes

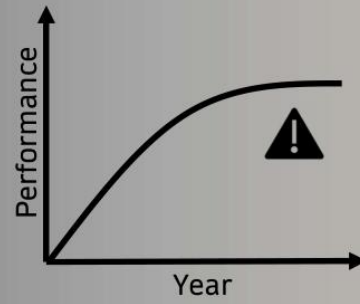
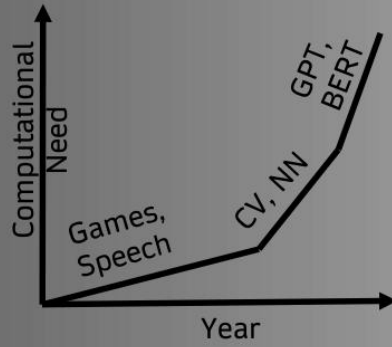
Robot Position

— Here I am!



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Towards Faster, Greener & 'Cooler' Tomorrow

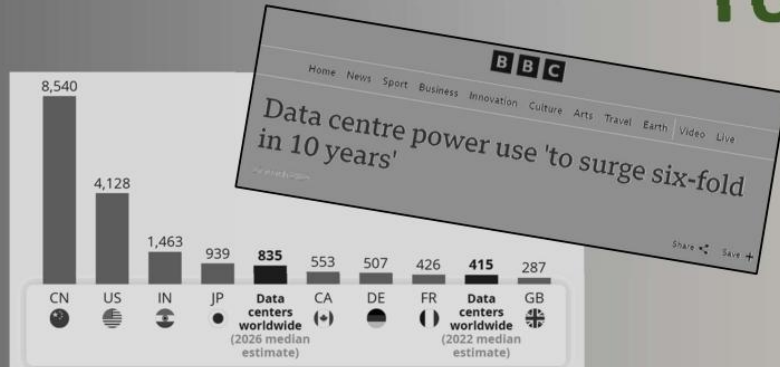
10x Faster!

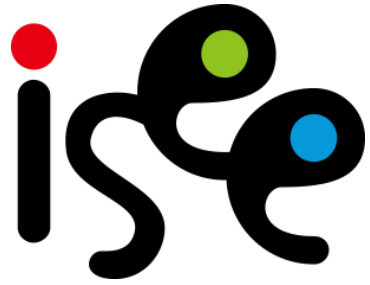
10x Lower Power!



Single Flux Quantum based systems

Best for data centres, servers & quantum systems





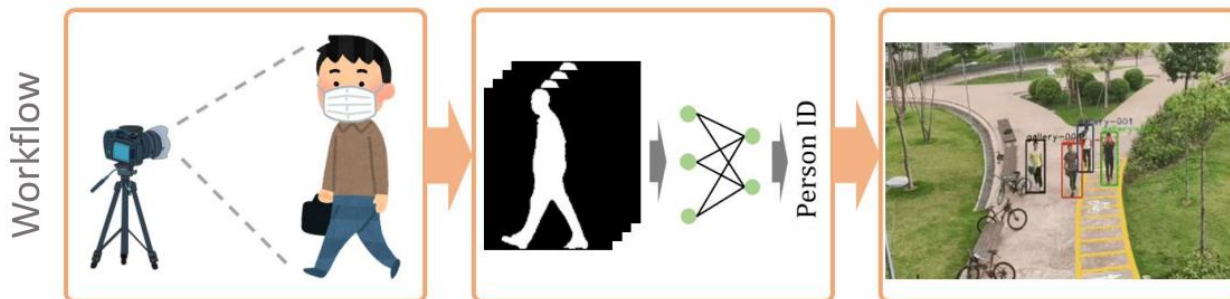
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3D Gait Shape Upsampling using Diffusion Models for LiDAR-based Gait Recognition

(1) What is gait recognition?

- Identifying people based on their **walking patterns**
- Operates from a distance** without user's cooperation/contact

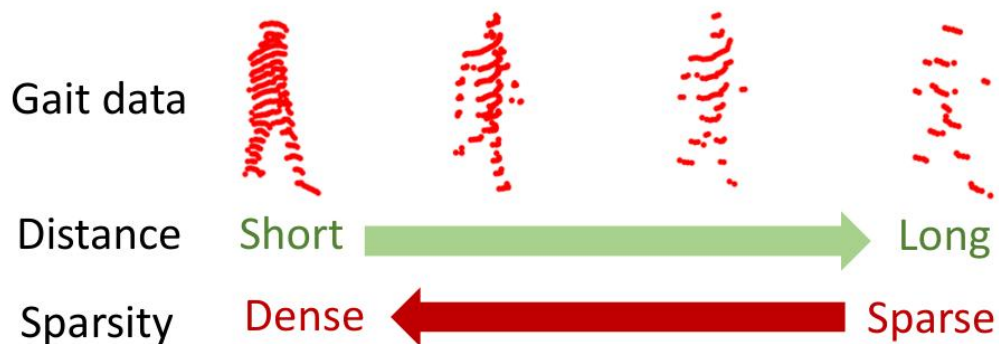


Typical visual device is an **RGB camera**

(2) Why is a LiDAR sensor good at gait recognition?

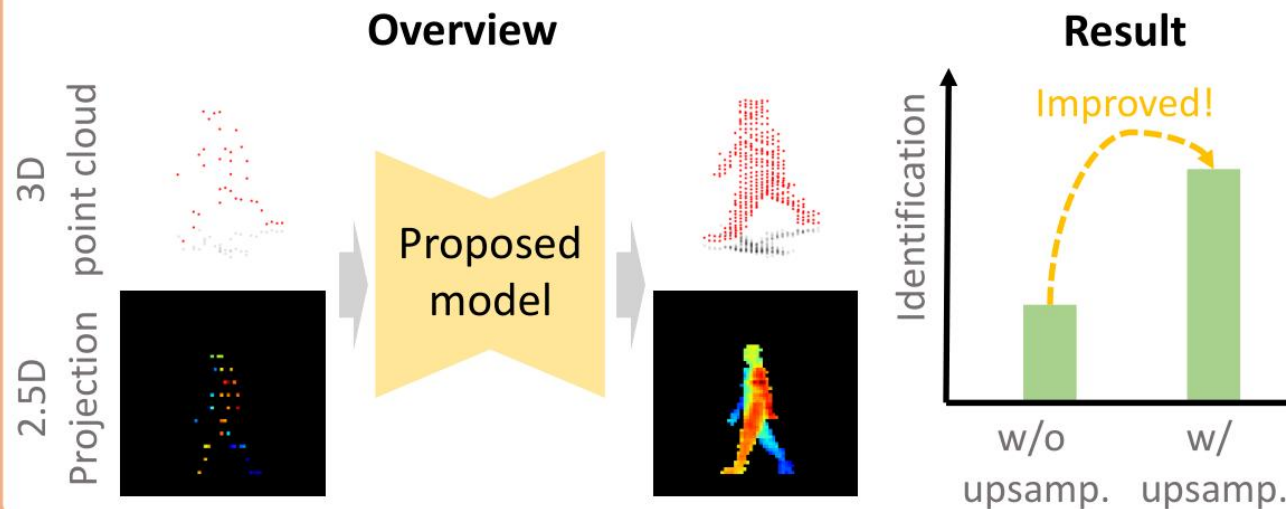
Visualization	RGB camera	LiDAR sensor
	2D	3D
	Narrow	Wide
	Unstable	Robust
	Dimension	Dimension
	Field-of-View	Field-of-View
	Illumination	Illumination

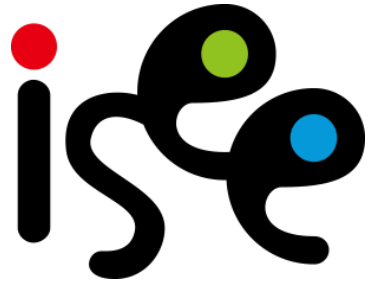
(3) What is the weakness of the LiDAR sensor?



Sparse gait data **reduces identification performance!**

(4) Goal: Upsample to restore complete gait data



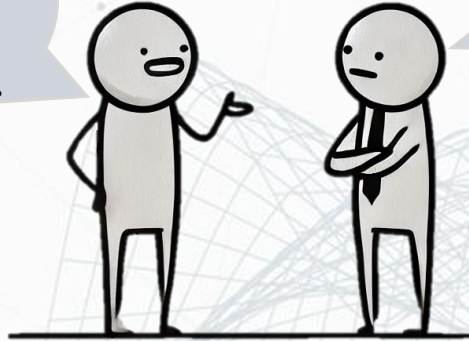


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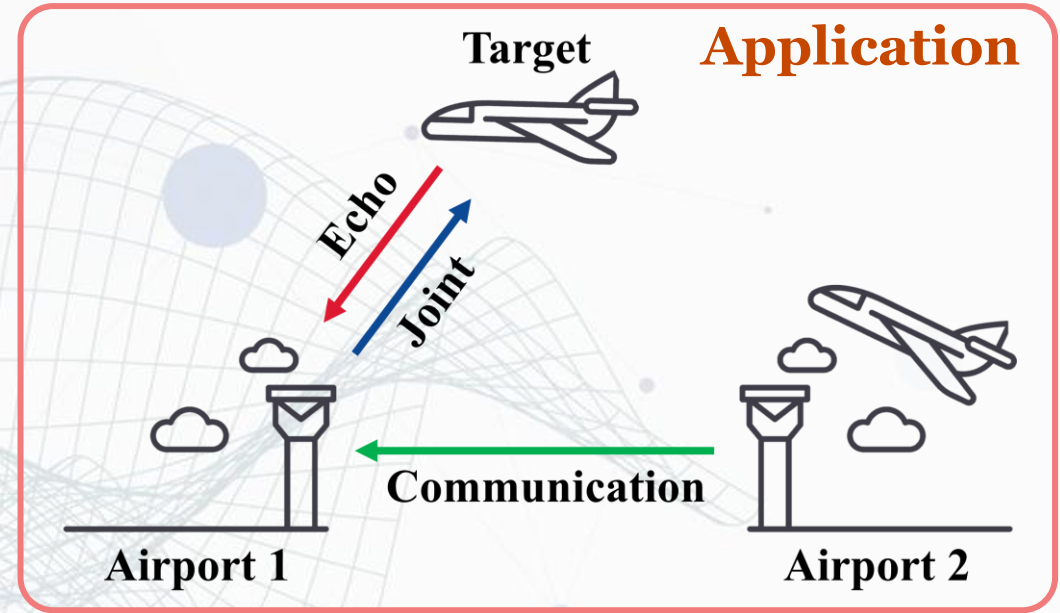
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Joint Communication and Sensing (JCAS)

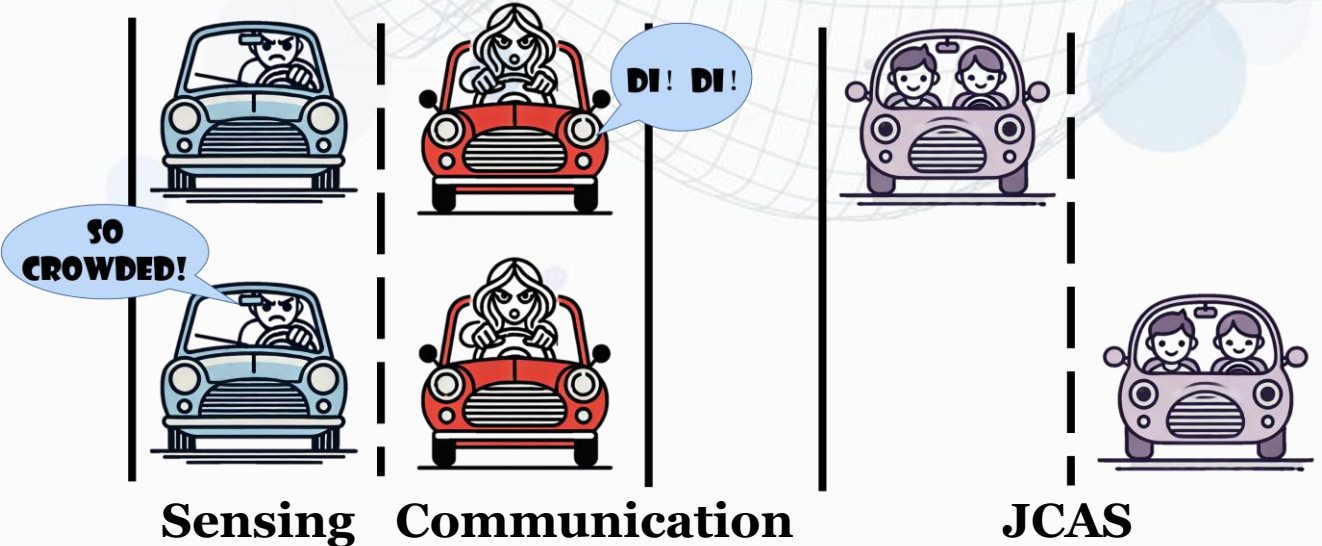
6G technology is amazing, but they require a lot of spectrum resources.



Why not solve it through multiplexing?



Principle

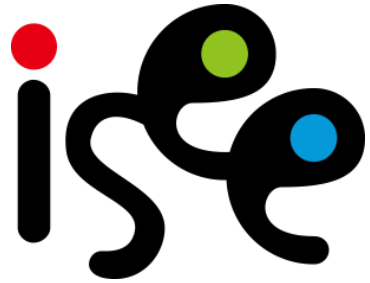


JCAS not only integrates the sensing and communication together to save spectrum, but also improve both of their abilities!



JITSUMATSU LAB.

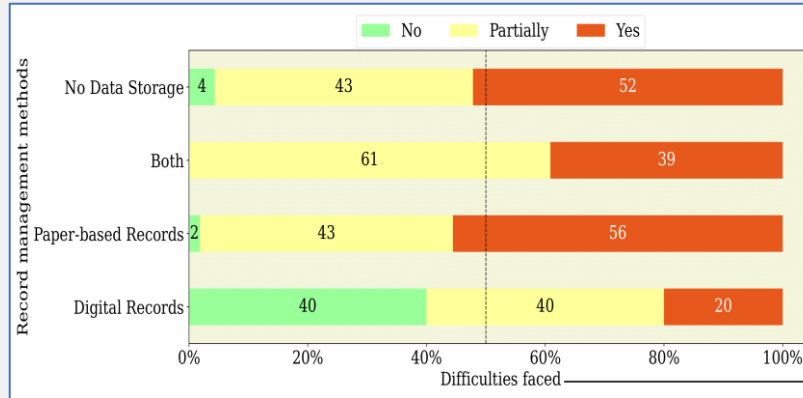
Want to know more? Follow this lab!



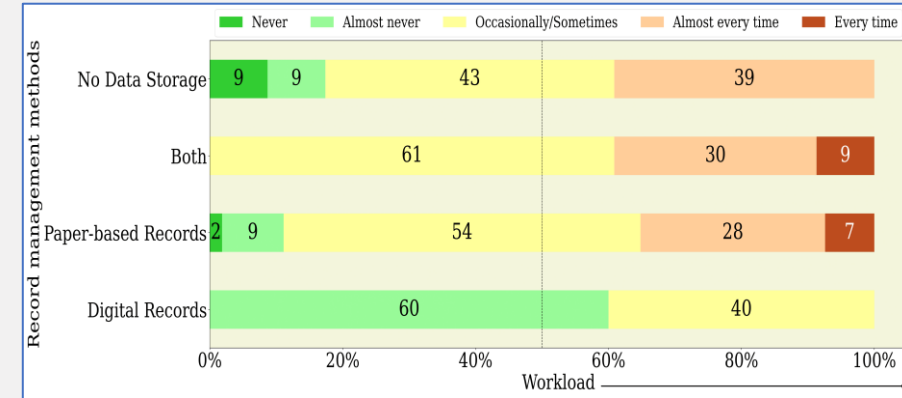
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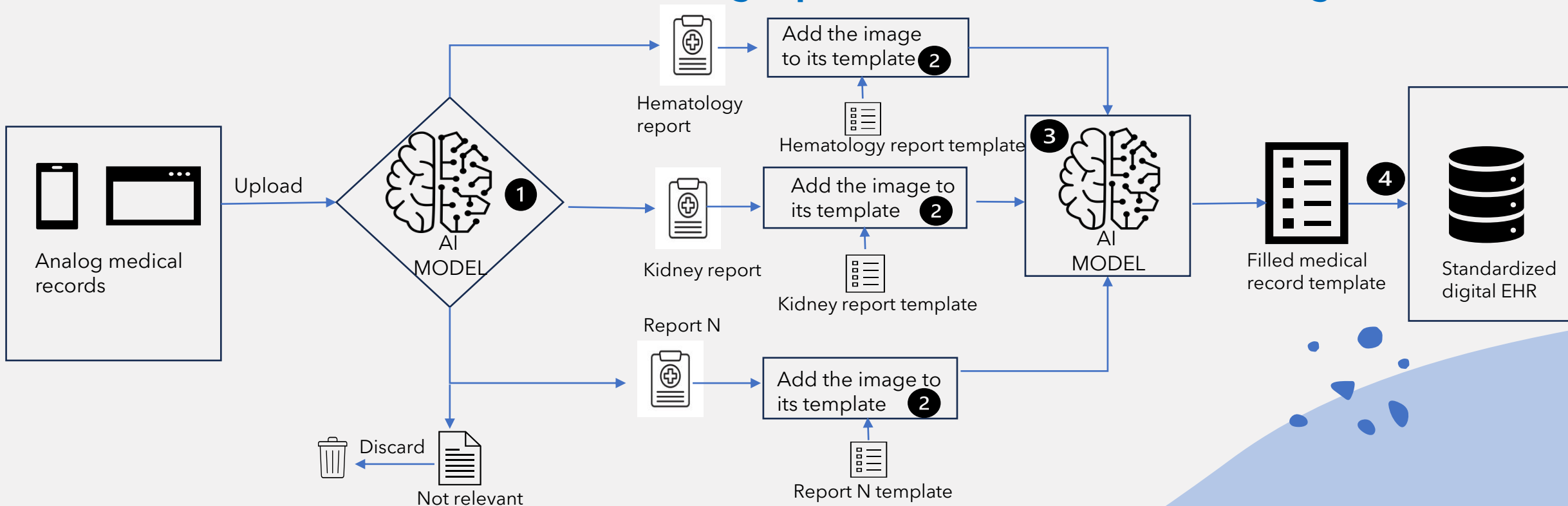
Clinical decision making

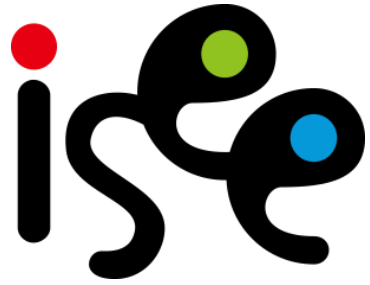


Workload



An AI driven solution for Transforming Paper-Based Medical Records into Digital Formats





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Beyond the Surface: Bridging Human Insights & AI in Education

Menna Fateen
Mine Laboratory

73%

Limit #1

Breakthrough?
Decline?

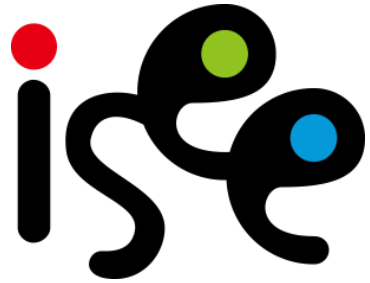
TOPP: Teacher Observations
for Performance Prediction

Limit #2

Generic
Feedback 🤔

RAG for Teacher-Aligned
Formative Feedback





Time for Voting

URL for Vote



Indoor Robot Localization with Wireless Distance Sensors	Tomoya Itsuka
Towards Faster, Greener & 'Cooler' Tomorrow	Pratiksha Mundhe
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Please finish voting by 10:20 am.

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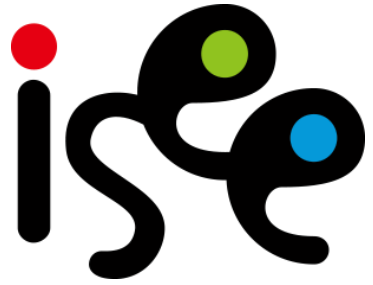
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	1st 1位	2nd 2位	3rd 3位
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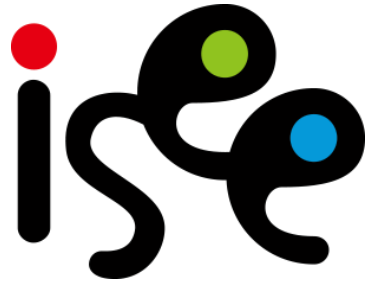


ISEE 3MT

Award Celebration & Closing

from

Prof. Ryo Kurazume



ISEE 3MT

Awards

<i>1st</i>	
<i>2nd</i>	
<i>3rd</i>	